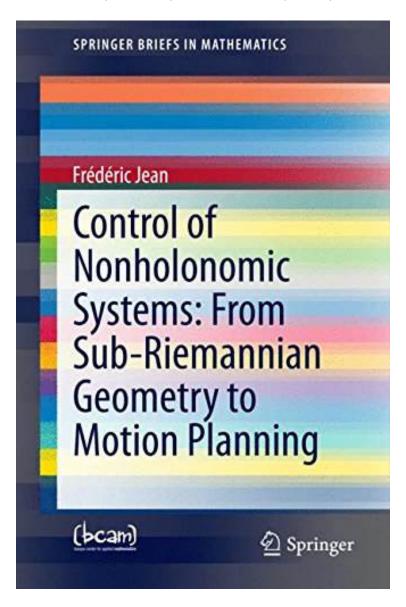
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# **Control of Nonholonomic Systems: from Sub-Riemannian Geometry to Motion Planning (SpringerBriefs in Mathematics)**

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